

Coq/Ssreflect for large case-based graph theory proofs

Ricardo Katz (CIFASIS-CONICET)

Daniel Severín (UNR, CONICET)

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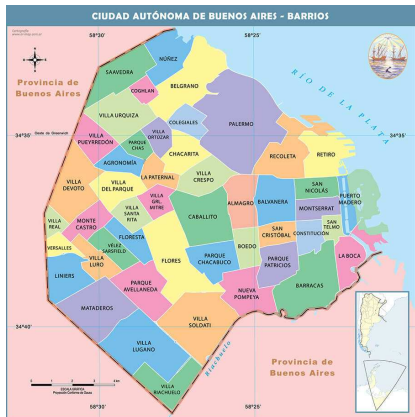
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- exploring the possibility of generating certificates about the value of the parameter for a given instance.

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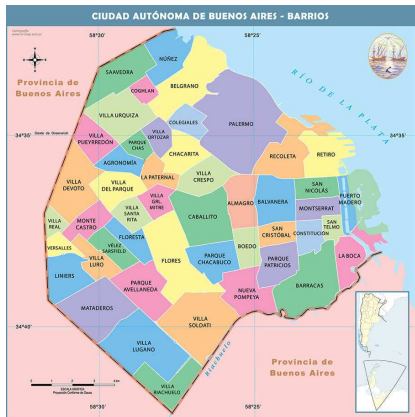
Disclaimer: we are by no means experts in the field

An example



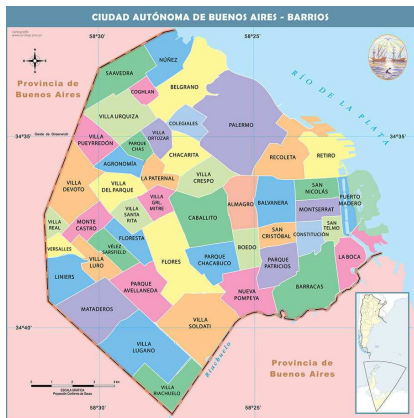
- Consider a city divided into areas where a service wants to be provided (e.g., mobile phone connection).

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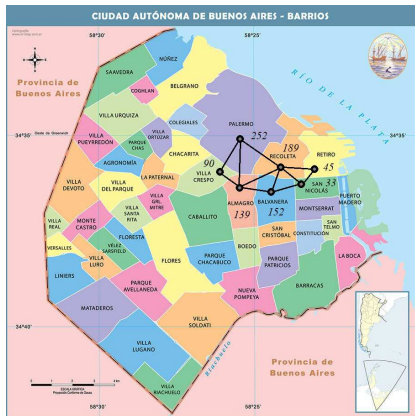
- Consider a city divided into areas where a service wants to be provided (e.g., mobile phone connection).
- Assume the service is properly provided to the area in which it is located and its neighbors.

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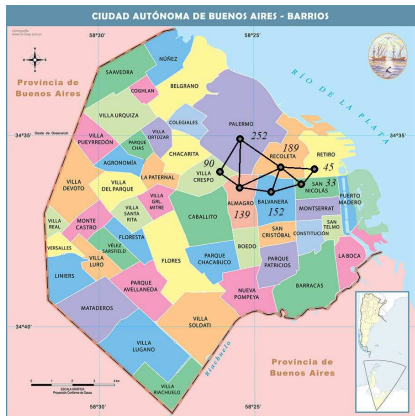
- Consider a city divided into areas where a service wants to be provided (e.g., mobile phone connection).
- Assume the service is properly provided to the area in which it is located and its neighbors.
- If each allocation of the service has a fixed high cost, no allocation to an area is desired if all the areas covered by this allocation are covered by other allocated areas.

An example

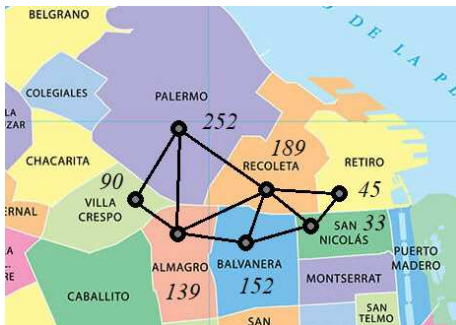


- The city is modeled by a graph whose vertices are the areas and there is an edge between two vertices if the corresponding areas are neighbors.

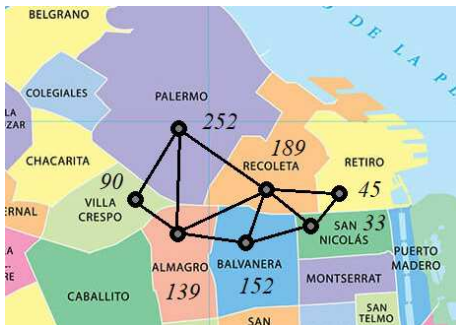
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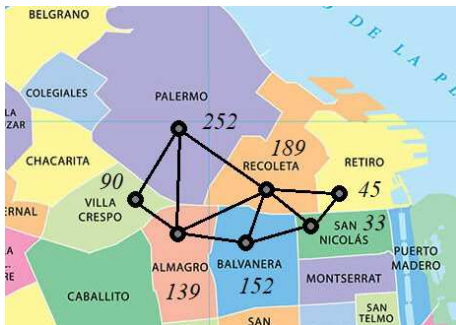
- The city is modeled by a graph whose vertices are the areas and there is an edge between two vertices if the corresponding areas are neighbors.
- There is a value associated with each area representing the profit of installing the service there.



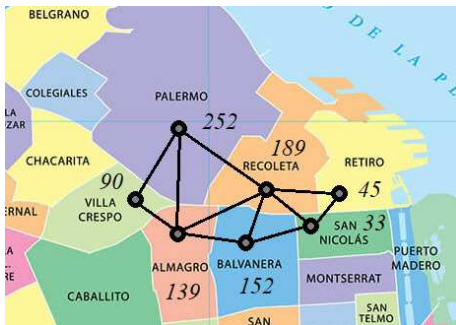
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 - ▶ ...if it is required that all areas are covered
 - Weighted Upper Domination Set (WUDS) $\Gamma_w(G)$
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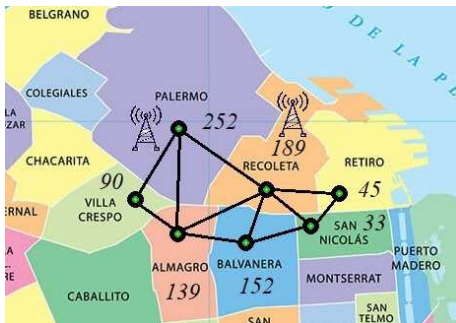


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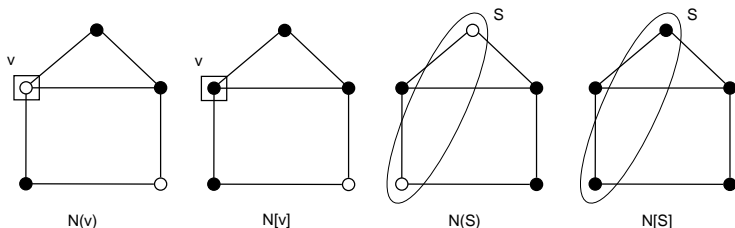
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- $S \subseteq V$
 - ▶ $N(S) \doteq \bigcup_{v \in V} N(v)$
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- open neighborhood
closed neighborhood



Stable (or independent) sets

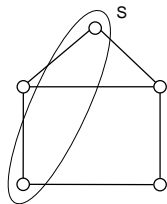
A set $S \subseteq V$ is *stable* if no vertex in S is adjacent to any other in S

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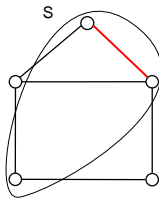
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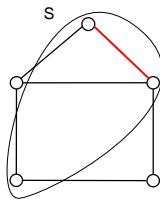
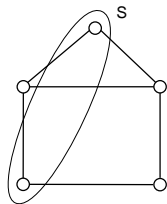


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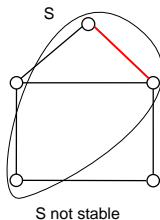
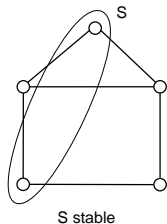


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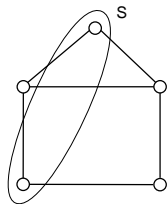
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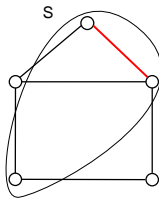
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$\alpha(G)$ = stable set of maximum size

- $w(v)$ = weight of vertex v
- $w(S) = \sum_{v \in S} w(v)$ weight of set S

$\alpha_w(G)$ = stable set of maximum weight

Irredundant sets

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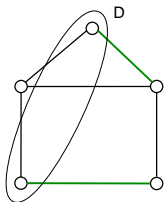
- D irredundant $\iff \forall v \in D, N[v] - N[D - \{v\}] \neq \emptyset$

Irredundant sets

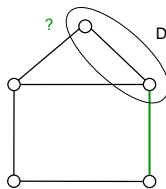
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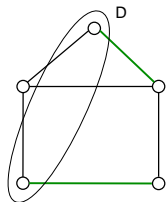
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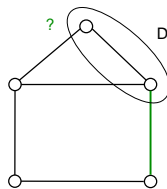
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D irredundant



D not irredundant

- $IR(G)$ = irredundant set of maximum size
- $IR_w(G)$ = irredundant set of maximum weight

Dependencies used in the formalization

Requirements: Coq 8.11+, MathComp 1.10+
graph-theory 0.8 [Doczkal, Pous 2020]

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- In particular, the definitions of parameters α_w and IR_w were previously formalized in graph-theory library [S.- 2019]:

```
Variable G : sgraph.
```

```
Variable weight : G → ℕ.
```

```
Definition weight_set S := \sum_(v ∈ S) weight v.
```

```
Definition α_w := weight_set (arg_max ∅ stable weight_set).
```

```
Definition IR_w := weight_set (arg_max ∅ irredundant weight_set).
```

(G denotes the graph and its set of vertices as well, due to a coercion)

Our work

An upper bound

$$IR_w(G) \leq w(V) - \delta_w(G),$$

$$\text{where } \delta_w(G) \doteq \min\{w(N[v] \setminus \{u\}) : v \in V, u \in N[v]\}$$

(particular case: $\delta_1(G)$ = minimum degree of G)

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```
Let M n := (G == ∅) || [∃v, [∃u, (u ∈ N[v]) && (W(N[v] : \ u) == n)]].
```

```
Fact exM : ∃ n : ℕ, M n.
```

```
Definition δ_w := ex_minn exM.
```

```
Fact delta_w_min u v : (u ∈ N[v]) → δ_w ≤ W (N[v] : \ u).
```

```
Lemma bound_weight_irredundant S :  
  (irredundant S) → W S ≤ W G - δ_w G.
```

```
Proof. (12 lines) Qed.
```

```
Lemma IR_w_leq_V_minus_delta_w : IR_w G weight ≤ W G - δ_w G.
```

Our work

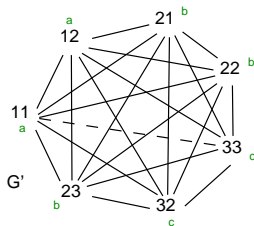
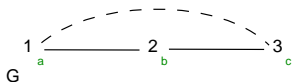
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- ▶ $u \text{ *-} v \doteq u$ dominates v ▶ $(G' = (V', E'), w')$
 - ▶ $V' \doteq \{uv : u \in V, u \text{ *-} v\}$,
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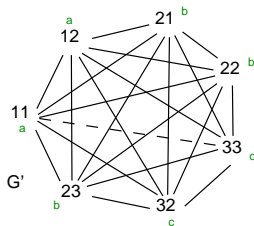
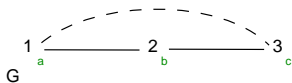
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A transformation between MWIS and Max. Weighted Stable Set Problem

$$IR_w(G) = \alpha_{w'}(G')$$

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```
Inductive trfgraph_vert_type :=  
  TrfGraphVert (x : G * G) of (x.1 *- x.2).
```

```
Definition trfgraph_rel := [rel x y : trfgraph_vert_type | (x != y)  
  && ((y.1 *- x.2) || (y.2 *- x.1))].
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Definition trfgraph := SGraph trfgraph_sym trfgraph_irrefl.
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Let G' := trfgraph G.  
Let weight' := λ x : G', weight x.1.
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Theorem IR_w_G_is_alpha_w_G' : IR_w G weight = alpha_w G' weight'.
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(300 total lines)

Our work

- ▶ $G \dot{\subset} H \doteq G$ is an induced subgraph of H

Basic properties of induced subgraphs

- $S \subset V(G) \implies G[S] \dot{\subset} G$
- $G_1 \dot{\subset} G_2 \wedge G_2 \dot{\subset} G_3 \implies G_1 \dot{\subset} G_3$

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Definition `induced_subgraph (G1 G2 : sgraph) :=
exists2 h : G1 → G2, injective h & induced_hom h.`

Notation `"A $\dot{\subset}$ B" := (induced_subgraph A B).`

Lemma `induced_S_is_sub G (S : {set G}) : (induced S) $\dot{\subset}$ G.`

Lemma `subgraph_trans G1 G2 G3 : G1 $\dot{\subset}$ G2 → G2 $\dot{\subset}$ G3 → G1 $\dot{\subset}$ G3.`

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(would be great if some properties about induced subgraphs could be added to graph-theory library 😊)

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Lemma `subgraph_G_G' G : G \dot{\subset} trfgraph G.`

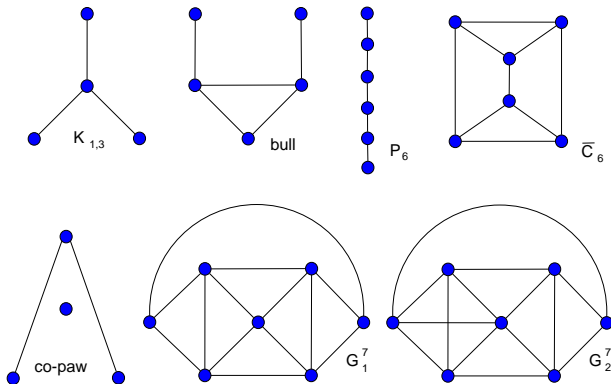
Lemma `trfgraph_subgraph G H :`
`G \dot{\subset} H \to trfgraph G \dot{\subset} trfgraph H.`

(70 total lines)

Our work

Main results (used for complexity results of MWIS)

- $[K_{1,3}]$: $K_{1,3} \dot{\subset} G \vee \text{bull} \dot{\subset} G \vee P_6 \dot{\subset} G \vee \overline{C}_6 \dot{\subset} G \iff K_{1,3} \dot{\subset} G'$
- $[\text{co-paw}]$: $\text{co-paw} \dot{\subset} G \vee G_1^7 \dot{\subset} G \vee G_2^7 \dot{\subset} G \iff \text{co-paw} \dot{\subset} G'$



The easy part

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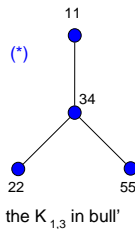
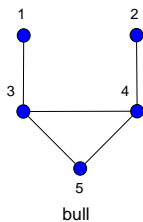
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- $[K_{1,3}]$: $K_{1,3} \dot{\subset} G \vee \text{bull} \dot{\subset} G \vee P_6 \dot{\subset} G \vee \overline{C_6} \dot{\subset} G \iff K_{1,3} \dot{\subset} G'$
- $[\text{co-paw}]$: $\text{co-paw} \dot{\subset} G \vee G_1^7 \dot{\subset} G \vee G_2^7 \dot{\subset} G \iff \text{co-paw} \dot{\subset} G'$

\implies

$$\left. \begin{array}{l} (*) \longrightarrow K_{1,3} \dot{\subset} \text{bull}' \\ \text{bull} \dot{\subset} G \implies \text{bull}' \dot{\subset} G' \end{array} \right\} \implies K_{1,3} \dot{\subset} G'$$



The easy part

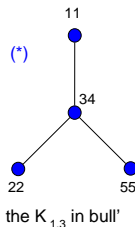
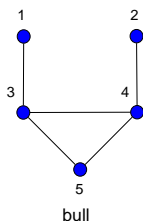
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- $[K_{1,3}]$: 70 lines
- $[\text{co-paw}]$: 40 lines



The hard part

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 - ▶ $[K_{1,3}]$: 4400 lines 🤖
 - ▶ $[\text{co-paw}]$: 1600 lines

Certificates

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[Rebennack et al. 2011]

Table 1 Computational results on DIMACS graphs

Instances				Branch & Cut		
Name	$ V $	Dens.	α	LB _{root}	LP value in root	
				BC	BC	BC _{rank}
brock200_2	200	0.50	12	12	20.99	22.01
brock200_4	200	0.34	17	14	29.93	31.54
brock400_2	400	0.25	29	22	63.84	67.66
brock400_4	400	0.25	33	23	63.89	67.98
c_fat200-1	200	0.92	12	12	12.71	12.86
c_fat200-2	200	0.84	24	22	24.00	24.00

Table 2

Values and bounds for $\chi_p^{d,n}(\mathbb{Z}_2, \mathbb{Z}_2)$.

$d \setminus n$	1	2	3
1	13-15	2	2
2	∞	12-18 ⁽¹⁾	8
3	∞	∞	16-22 ⁽²⁾
4	∞	∞	44-97 ⁽²⁾
5	∞	∞	199-?
6	∞	∞	∞

[Korže et al. 2019]

For the sake of interest, the following table gives some bounds computed by using these approaches.

[Goddard et al. 2008]

n	6	7	8	9	10	11
$\chi_b(Q_n) \geq$	15	28	63	132	285	610
$\chi_b(Q_n) \leq$	25	49	95	219	441	881

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- We can take advantage of the formalized theory to generate Coq files that certifies a value/bound of graph parameters; here, $IR_w(G)$

Certificates

$IR_w(G) \geq b$ (obtained by an heuristic)

unweighted Name	$ V(G) $	b	Time (s.)	unweighted Name	$ V(G) $	b	Time (s.)
myciel3	11	5	0.7	4-Insertions_3	79	38	8.8
myciel4	23	11	0.8	3-FullIns_3	80	37	8.2
queen5_5	25	5	0.4	jean	80	38	8.0
1-FullIns_3	30	14	1.1	queen9_9	81	13	1.8
queen6_6	36	7	0.6	david	87	36	6.9
2-Insertions_3	37	18	1.6	mug88_1	88	33	6.5
myciel5	47	23	3.0	mug88_25	88	33	6.4
queen7_7	49	9	0.9	1-FullIns_4	93	45	14.5
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queen8_8	64	11	1.4	mug100_1	100	36	7.6
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Roadmap:

- ▶ Propose an integer programming model for the parameter ✓
- ▶ Solve an instance via B&B emphasizing reducing size of the tree ✓
- ▶ Formalize concepts about linear programming [Allamigeon, Katz 2019]
- ▶ ...about integer programming and B&B resolution
- ▶ ...and perform the generator that uses the “trace” left by the solver

Thanks!

A bit of history

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- [McRae 1994] Several (NP-completeness) complexity results were given for Γ and IR
- Up to 2002, as reported by [Favaron et al. 2002], more that 1500 research papers about dominating sets have been published; in particular, more than 100 explore properties of irredundant sets in graphs. Research in these topics are still active, e.g. [Monnot, Fernau, Manlove 2021]

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- [Brešar et al. 2014] Results about Grundy domination parameter γ_{gr} ; Γ , IR and γ_{gr} are 3 points of view that model the worst case of a greedy heuristic that finds a dominating set; also $IR(G) \leq \gamma_{gr}(G)$

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Regarding weighted parameters:

- [Boyaci, Monnot 2017] Some complexity results about WUDS (Γ_w)
- [S.- 2019] Γ_w and IR_w (among other parameters) and the proof of $\Gamma_w(G) \leq IR_w(G)$ were formalized in Coq/Ssreflect

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